## Surface Modification, Magnetic Field and Solvent Effects in Magnetoactive Elastomer Composites

Lucija Drempetić<sup>a,b</sup>, Darko Makovec<sup>a</sup>, Darja Lisjak<sup>a</sup>

<sup>a</sup>Jožef Stefan Institute, Jamova 39, 1000 Ljubljana, Slovenia <sup>b</sup>Jožef Stefan International Postgraduate School, Jamova 39, 1000 Ljubljana, Slovenia

Magnetoactive elastomers (MAEs) are a class of soft composite materials composed of magnetic nano- or microparticles embedded within polymer matrices, capable of dynamically altering their mechanical behavior in response to external magnetic fields [1,2]. This tunable response makes MAEs highly attractive for applications in soft robotics, adaptive actuators, and vibration damping systems [1–3]. However, limitations in reproducibility and a lack of comprehensive understanding of their structure–property relationship continue to hinder their broader application.

This study investigates the effects of filler concentration, surface modification, solvent environment, and magnetic field exposure during curing on the microstructure and mechanical properties of MAEs based on a polydimethylsiloxane (PDMS) matrix with hexaferrite (HF) fillers. A primary focus is on preventing particle agglomeration and improving both filler distribution and compatibility with the polymer matrix. Surface modification of strontium hexaferrite (Sr-HF) microparticles using dodecylbenzene sulfonic acid (DBSA) slightly reduces agglomeration and enhances distribution. However, the use of 1-butanol as a solvent introduces porosity due to evaporation, affecting the mechanical properties of MAEs. The application of an external magnetic field during curing promotes some alignment of filler particles, in contrast to the random filler distribution observed in samples cured without a magnetic field. Rheological analysis reveals that 1-butanol, when used with scandium-substituted barium hexaferrite (BSHF) fillers, significantly delays curing (from 47 min in pure elastomer to 77 min in the MAE) and reduces crosslink density, thereby softening the polymer network (*G*' reduced from 7400 Pa to 3500 Pa). By systematically analyzing these effects and optimizing surface-modification strategy, this research aims to advance rational design of MAEs with programmable mechanical and magnetic responses.

Keywords: magnetoactive elastomers, hexaferrite, surface modification, soft robotics

## References

[1] S. A. Kostrov, M. R. Maw, S. S. Sheiko, 2023, Programming and Reprogramming the Viscoelasticity and Magnetic Response of Magnetoactive Thermoplastic Elastomers, *Polymers*, **15** (23), 4607.

[2] T. A. Nadzharyan, M. Shamonin, E. Y. Kramarenko, 2022, Theoretical Modeling of Magnetoactive Elastomers on Different Scales: A State-of-the-Art Review, *Polymers*, **14** (19), 4096.

[3] M. Xu, Y. Liu, J. Li, F. Xu, X. Huang, X. Yue, 2024, Review of Flexible Robotic Grippers, with a Focus on Grippers Based on Magnetorheological Materials, *Materials*, 17 (19), 4858.

Acknowledgment. This research has received funding from the European Union's Horizon Europe research and innovation programme under the Marie Skłodowska-Curie Actions Doctoral Network MAESTRI (grant agreement No. 101119614), and Slovenian Research and Innovation Agency through the research core funding P2-0089. Views and opinions expressed are however those of the authors only and do not necessarily reflect those of the European Union or the European Research Executive Agency. Neither the European Union nor the granting authority can be held responsible for them.

